

マーク付き点過程の欠損データのテスト及び補完

Detection and replenishment of missing data for marked point processes

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【Aim】 This project presents a fast approach for replenishing missing data in the record of a temporal point process with time separable marks, such as records of earthquakes and volcanic eruptions, in order to eliminate the underestimate of corresponding hazards caused by missing data.

【What is a point process】

Point process: random patterns of discrete events in space and/or time.

Marked point process: each event is assigned an attribute or size, namely a mark.

Conditional intensity: $\lambda(t, m | H_t) dt dm = \mathbf{E} [N([t, t + dt) \times (m, m + dm) | H_t)]$

Mark-separable marked point process: $\lambda(t, m | H_t) = \lambda_g(t | H_t) f(m)$

H_t : observation history up to time t .

【Bi-scale empirical transformation】

Bi-scale empirical transformation transforms a mark-separable point process

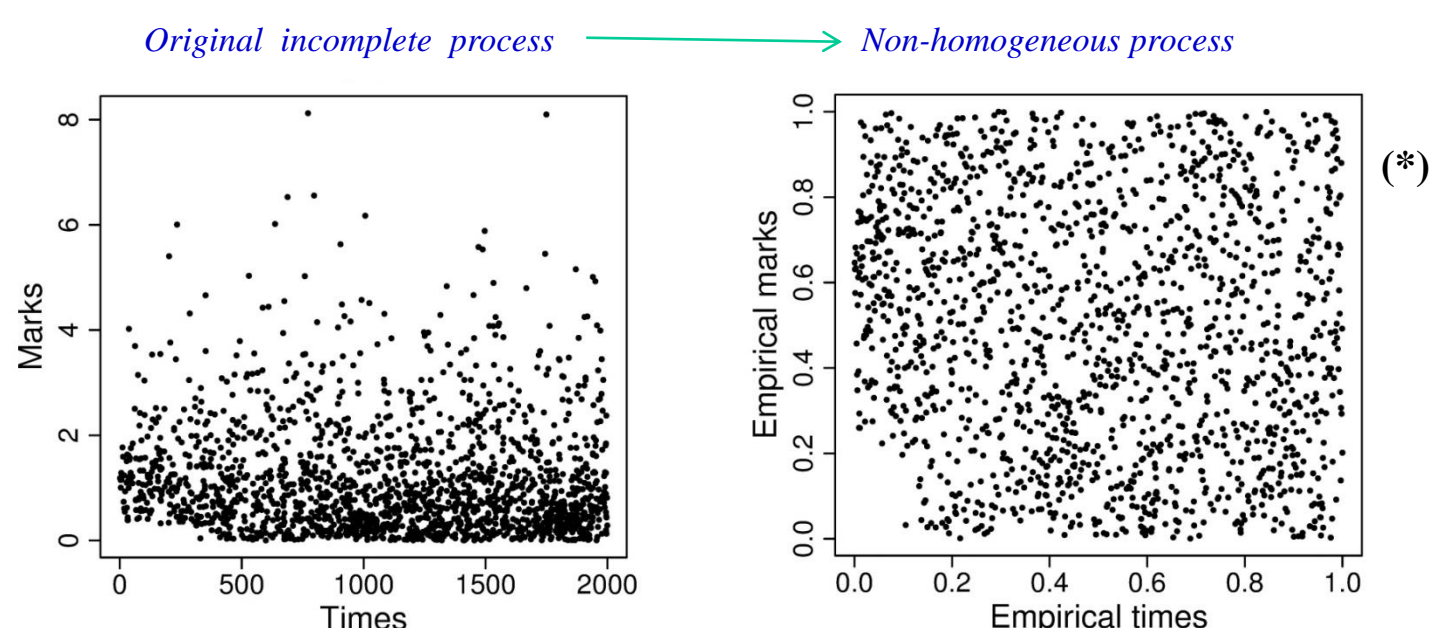
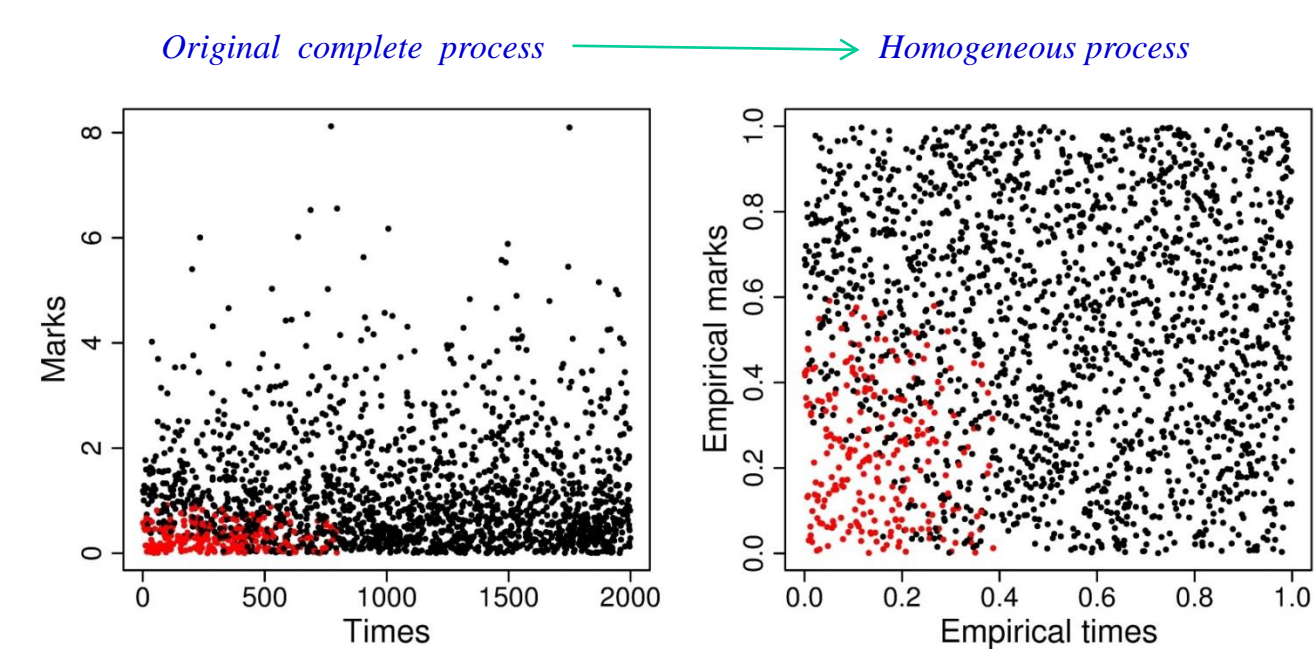
$N = \{(t_i, m_i) : i = 1, \dots, N\}$ on $[0, T] \times \mathbf{M}$

into a homogeneous pattern on the unit square.

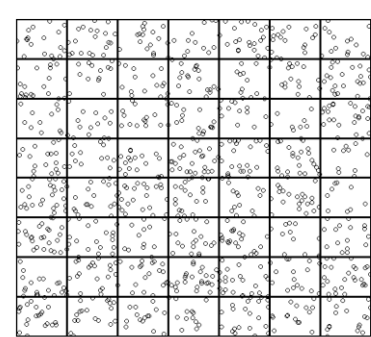
$$\Gamma: [0, T] \times \mathbf{M} \rightarrow [0, 1] \times [0, 1]$$

$$(t, m) \rightarrow (\tilde{F}(t), \tilde{G}(m))$$

$\tilde{F}(t), \tilde{G}(m)$: empirical distribution function of $\{t_i : i = 1, \dots, N\}$ and $\{m_i : i = 1, \dots, N\}$



【Testing methods】



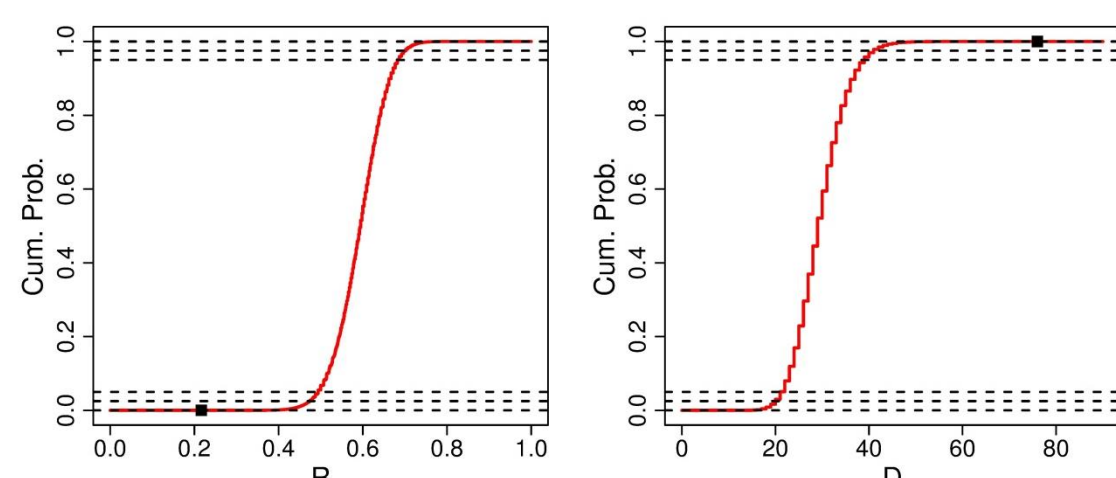
$$R = \frac{\min\{C_1, C_2, \dots, C_L\}}{\max\{C_1, C_2, \dots, C_L\}}$$

$$D = \max\{C_1, C_2, \dots, C_L\} - \min\{C_1, C_2, \dots, C_L\}$$

$$L = \text{#Row} \times \text{#Column}$$

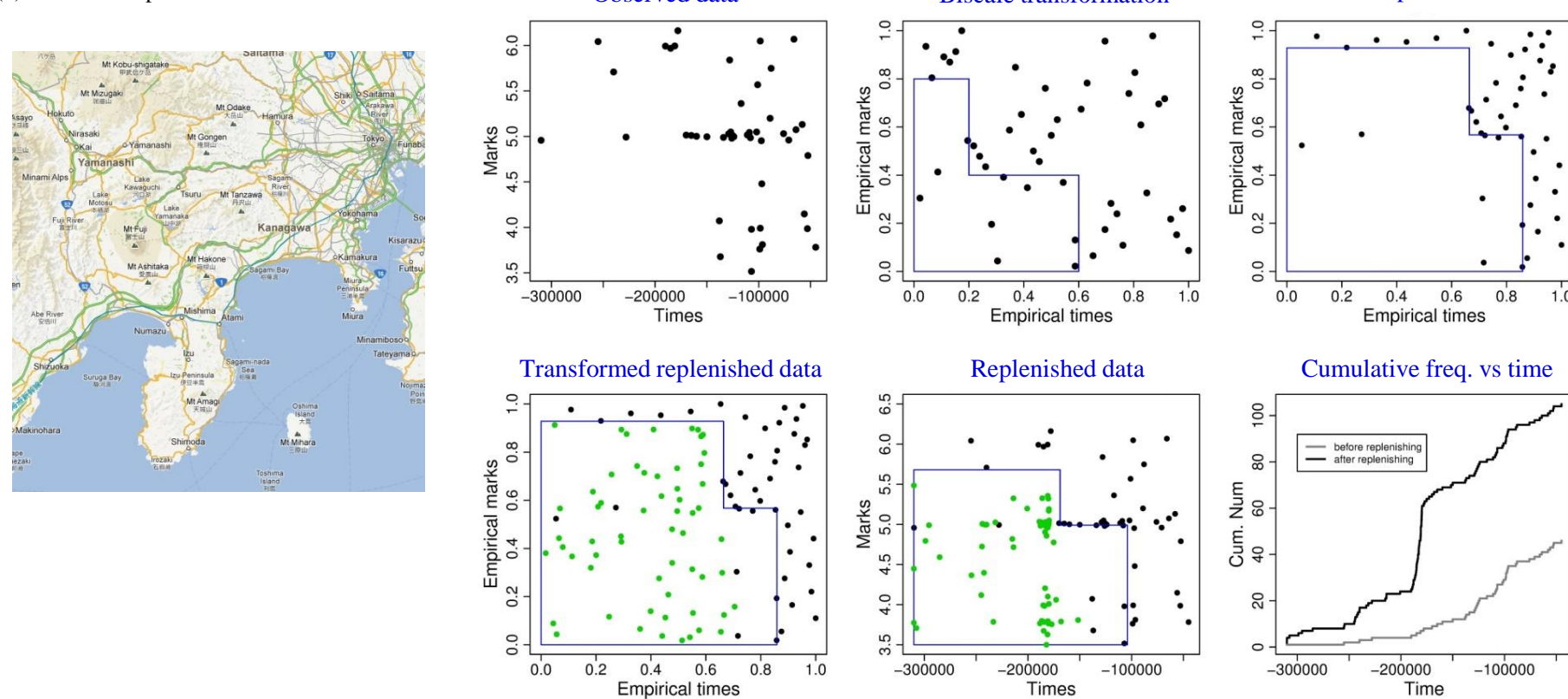
C_i : number of events at each cells

Testing results for (*)



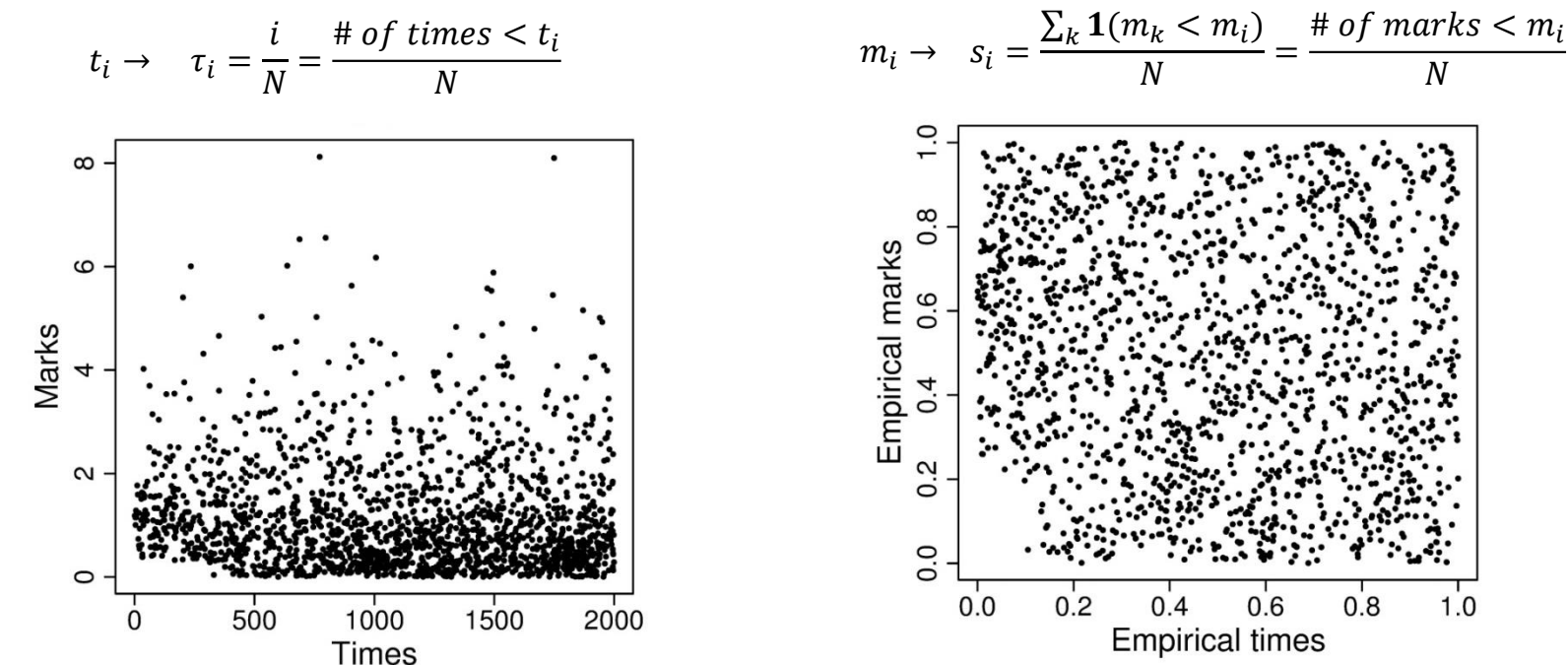
【Example 1: Eruptions at Hakone volcano】

Data source: (1) Smithsonian's Global Volcanism Program database (2) Large Magnitude Explosive Volcanic Eruptions database (LaMEVE database) (3) additional Japanese databases

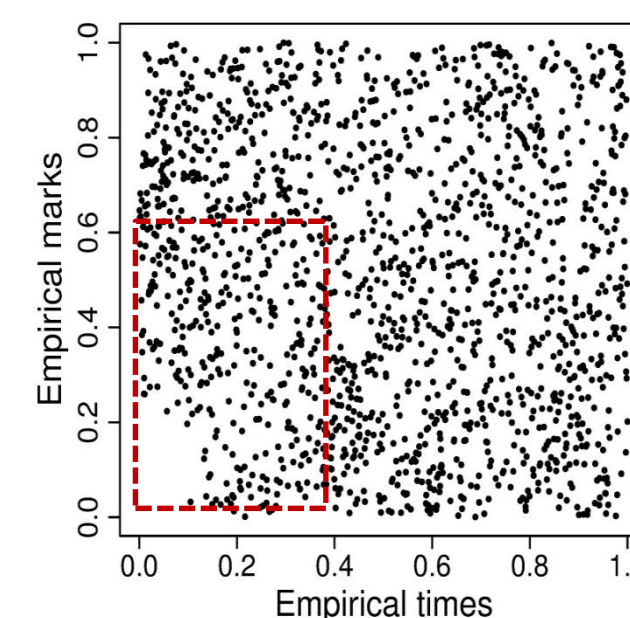


【Replenish Algorithm】

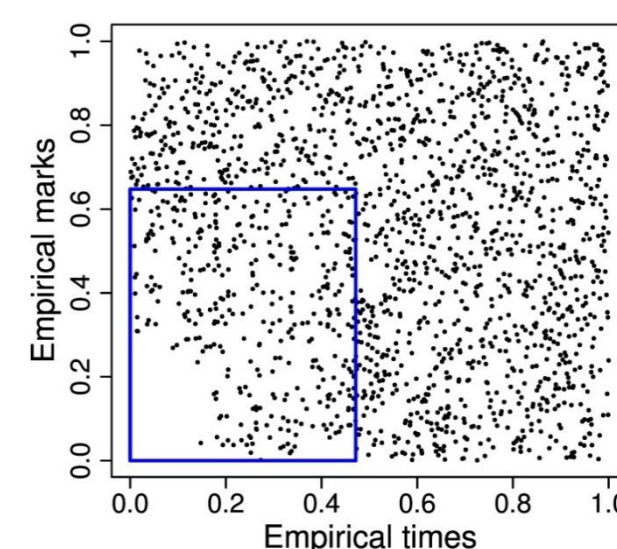
Step 1. Transform the process using the biscale empirical transformation.



Step 2. Specify area S that contains the missing data in the initial transformation domain.



Step 3. Calculate the missing area S^* in biscale transformation domain by solving



$$F_1^*(t) = \frac{\sum_{j=1}^n w_1(t_j, m_j, S) \mathbf{1}(t_j < t)}{\sum_{j=1}^n w_1(t_j, m_j, S)}$$

$$F_2^*(m) = \frac{\sum_{j=1}^n w_2(t_j, m_j, S) \mathbf{1}(m_j < m)}{\sum_{j=1}^n w_2(t_j, m_j, S)}$$

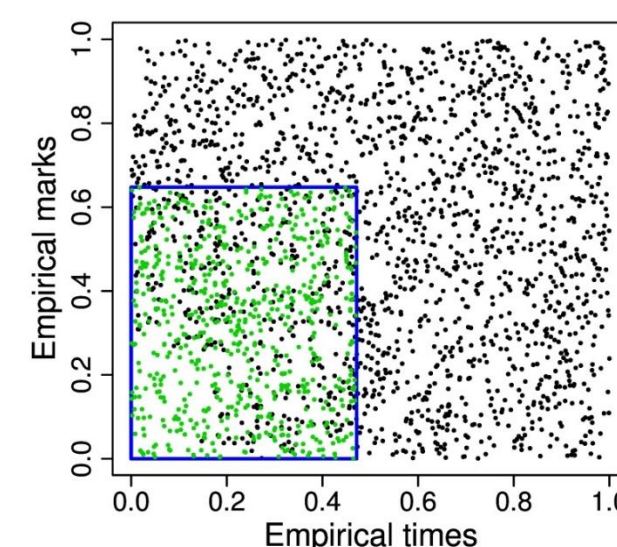
$$w_1(t, m, S) = \frac{\mathbf{1}((t, m) \notin S)}{\int_M \mathbf{1}((t, s) \notin S) dF_2^*(s)}$$

$$w_2(t, m, S) = \frac{\mathbf{1}((t, m) \notin S)}{\int_M \mathbf{1}((\tau, m) \notin S) dF_1^*(\tau)}$$

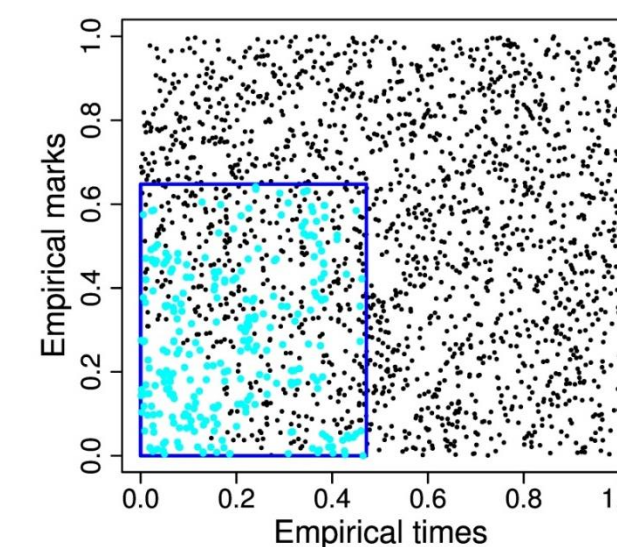
$$S^* = \{F_1^*(t), F_2^*(m) : (t, m) \in S\}$$

Step 4. Generate data point in the missing area

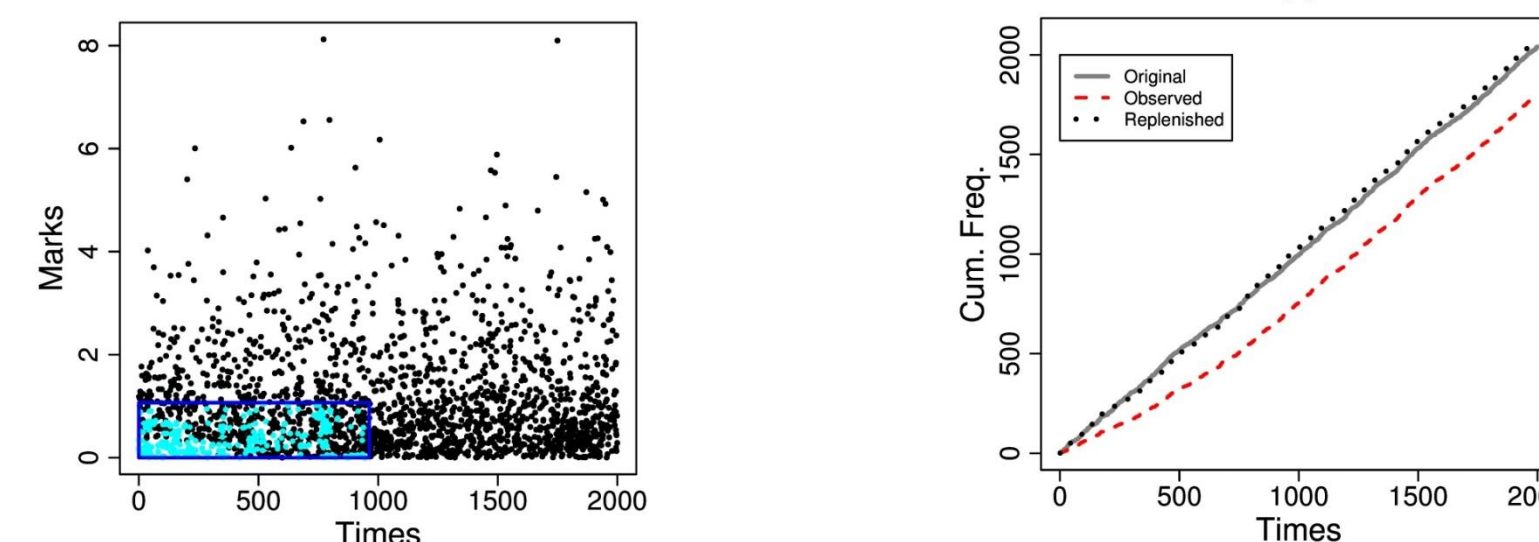
Generate events uniformly distributed in the missing region S^* (image of S)
events $\sim NB(k, 1 - |S^*|)$
 k : # of observed events outside of S^*



Step 5. Remove sequentially the closest simulated data point for each existing point in the missing area.



Step 5. Transform back all the events into the original domain



【Example 2: Recent Kumamoto earthquake sequence data】

Data: Japan Meteorological Agency catalog
Time: 2016/4/1~2016/4/21
Mag.: 1.0+
Depth: < 100 km
Space: E128° - 133°
N30° - 35°

